

# Probabilistic Graphical Models

## Lecture 10 – Undirected Models

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# Announcements

- Homework 2 due this Wednesday (Nov 4) in class
- Project milestones due next Monday (Nov 9)
  - About half the work should be done
  - 4 pages of writeup, NIPS format
  - <http://nips.cc/PaperInformation/StyleFiles>

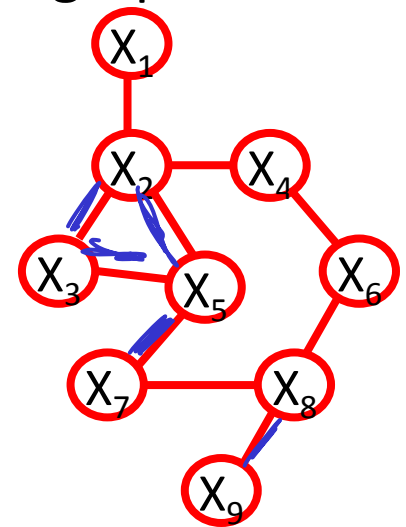
# Markov Networks

(a.k.a., Markov Random Field, Gibbs Distribution, ...)

- A Markov Network consists of
  - An undirected graph, where each node represents a RV
  - A collection of factors defined over cliques in the graph

- Joint probability

$$P(x) = \frac{1}{Z} \prod_i \psi_i(C_i)$$



- A distribution factorizes over undirected graph  $G$  if  
 $\exists$  factors  $\psi_1 \dots \psi_k$  over cliques of  $G$  s.t.  
$$P(x) = \frac{1}{Z} \prod_i \psi_i(C_i)$$

# Computing Joint Probabilities

- Computing joint probabilities in BNs

$$P(X_1, \dots, X_n) = \prod_i P(X_i | Pa_i)$$

$$P(X_i | X_n)$$

actually comp.  $P(X_i, X_n)$

$$Z = \sum_x \prod_i \psi_i(C_i)$$

- Computing joint probabilities in Markov Nets

$$P(\underline{X_1, \dots, X_n}) = \frac{1}{Z} \prod_i \psi_i(C_i)$$

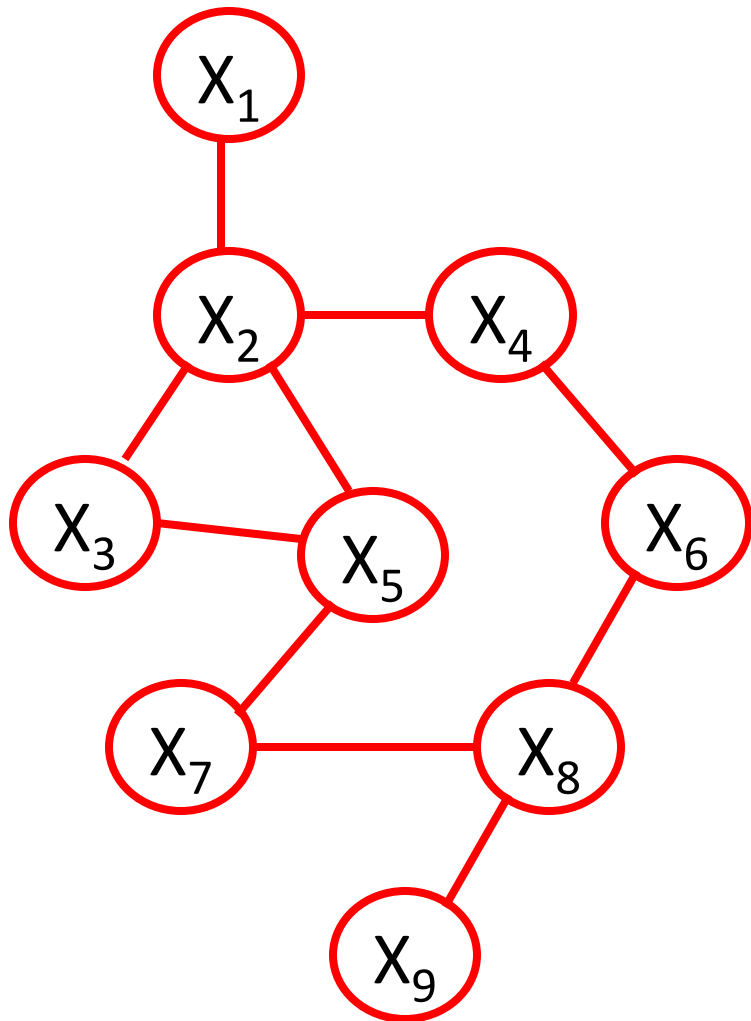
Need to know partition "function"  $Z$

Can do V.E.  
variable elimination

Can compute

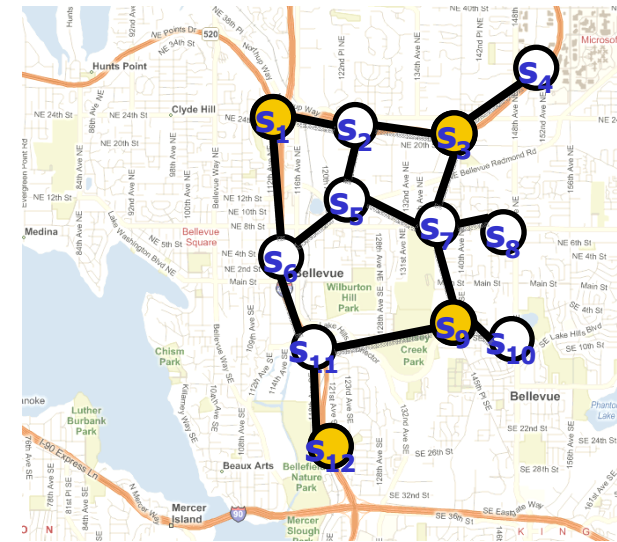
$$\frac{P(x_1, \dots, x_n)}{P(x'_1, \dots, x'_n)} = \frac{\prod_i \psi_i(C_i)}{\prod_i \psi_i(C'_i)}$$

# Local Markov Assumption for MN



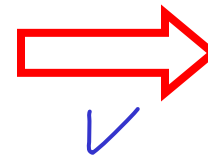
- The **Markov Blanket**  $\text{MB}(X)$  of a node  $X$  is the set of neighbors of  $X$
- Local Markov Assumption:  $X \perp \text{EverythingElse} \mid \text{MB}(X)$
- $I_{\text{loc}}(G)$  = set of all local independences
- $G$  is called an I-map of distribution  $P$  if  $I_{\text{loc}}(G) \subseteq I(P)$

# Factorization Theorem for Markov Nets “→”



True distribution  $P$   
can be represented exactly as  
a Markov net  $(G, P)$

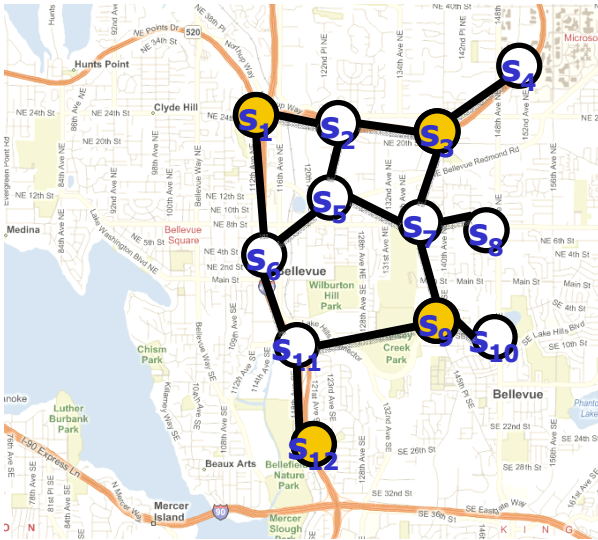
$$P(X_1, \dots, X_n) = \frac{1}{Z} \prod_i \phi_i(\mathbf{C}_i)$$



$$I_{\text{loc}}(G) \subseteq I(P)$$

$G$  is an **I-map** of  $P$   
(independence map)

# Factorization Theorem for Markov Nets “←” Hammersley-Clifford Theorem



True distribution  $P$   
can be represented exactly as

$$P(X_1, \dots, X_n) = \prod_i P(X_i \mid \mathbf{Pa}_{X_i})$$

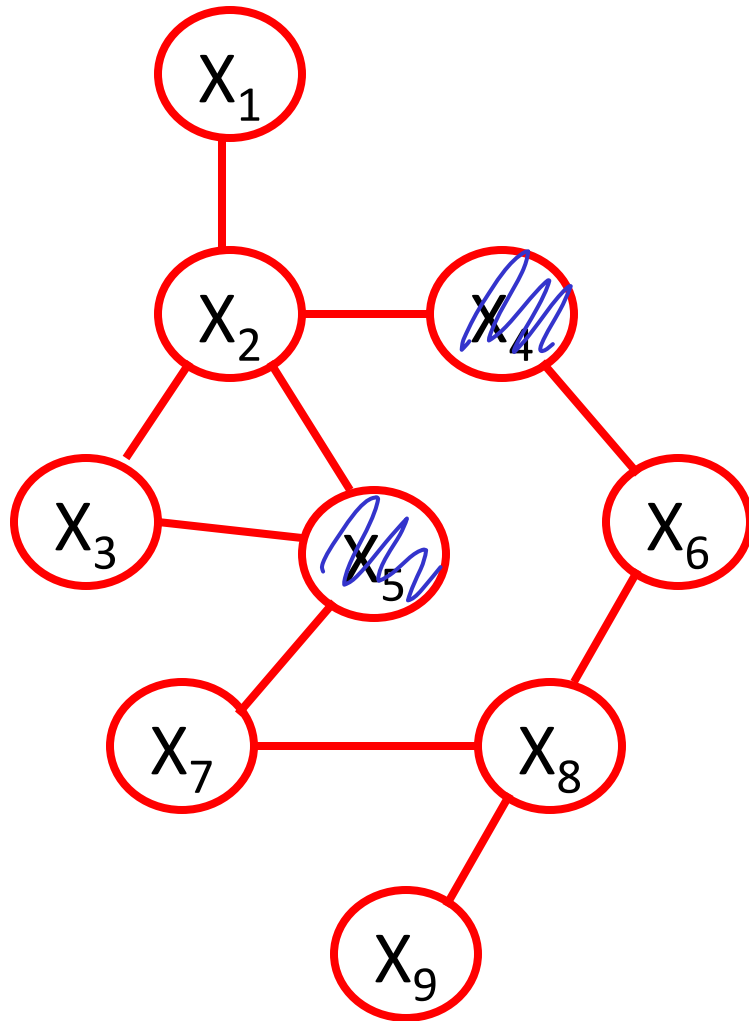
i.e.,  $P$  can be represented as  
a Markov net  $(G, P)$

$$I_{\text{loc}}(G) \subseteq I(P)$$



$G$  is an **I-map** of  $P$   
(independence map)  
and  $P > 0$

# Global independencies



- A trail  $X - \underline{X_1 - \dots - X_m} - Y$  is called active for evidence  $E$ , if none of  $X_1, \dots, X_m \in E$
- Variables  $X$  and  $Y$  are called **separated** by  $E$  if there is no active trail for  $E$  connecting  $X, Y$   
Write  $\text{sep}(X, Y \mid E)$
- $I(G) = \{X \perp Y \mid E: \text{sep}(X, Y \mid E)\}$



# Soundness of separation

- Know: For positive distributions  $P > 0$

$$I_{\text{loc}}(G) \subseteq I(P) \Leftrightarrow P \text{ factorizes over } G$$

- **Theorem:** Soundness of separation

For positive distributions  $P > 0$

$$I_{\text{loc}}(G) \subseteq I(P) \Leftrightarrow I(G) \subseteq I(P)$$

- Hence, separation captures only true independences
- How about  $I(G) = I(P)$ ?

# Completeness of separation

**Theorem:** Completeness of separation

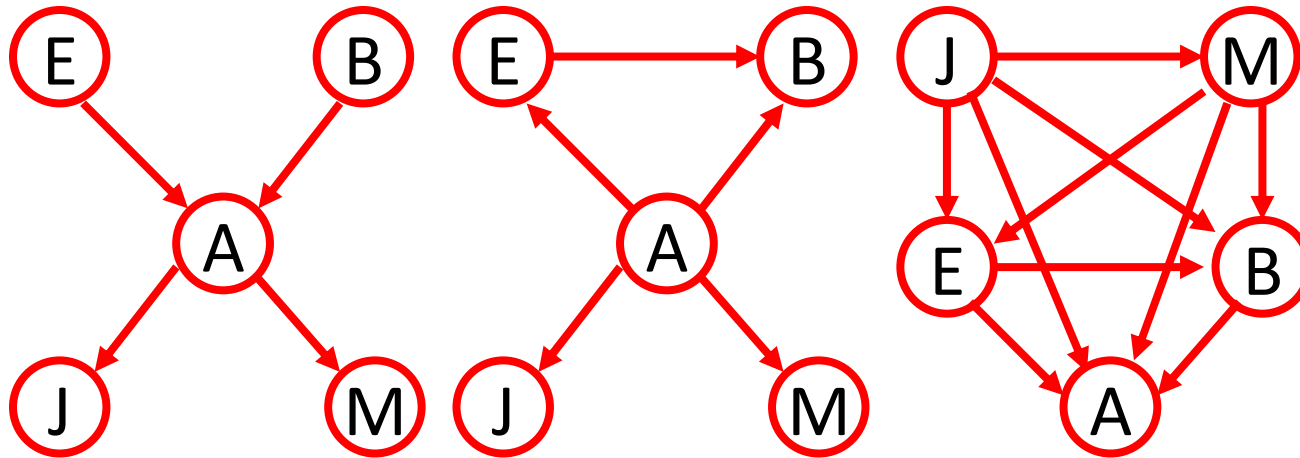
$$I(G) = I(P)$$

for “almost all” distributions  $P$  that factorize over  $G$

“almost all”: Except for of potential parameterizations of measure 0 (assuming no finite set have positive measure)

# Minimal I-maps

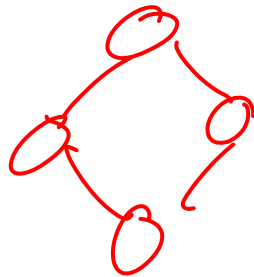
- For BNs: Minimal I-map not unique



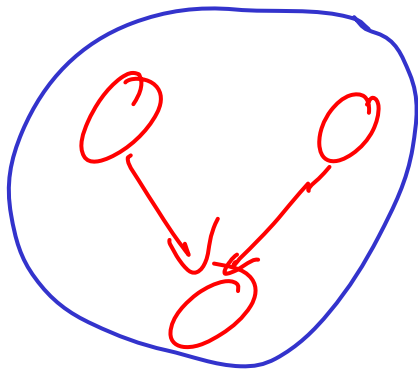
- For MNs: For positive P, minimal I-map is unique!!

# P-maps

- Do P-maps always exist?
- For BNs: no



- How about Markov Nets?



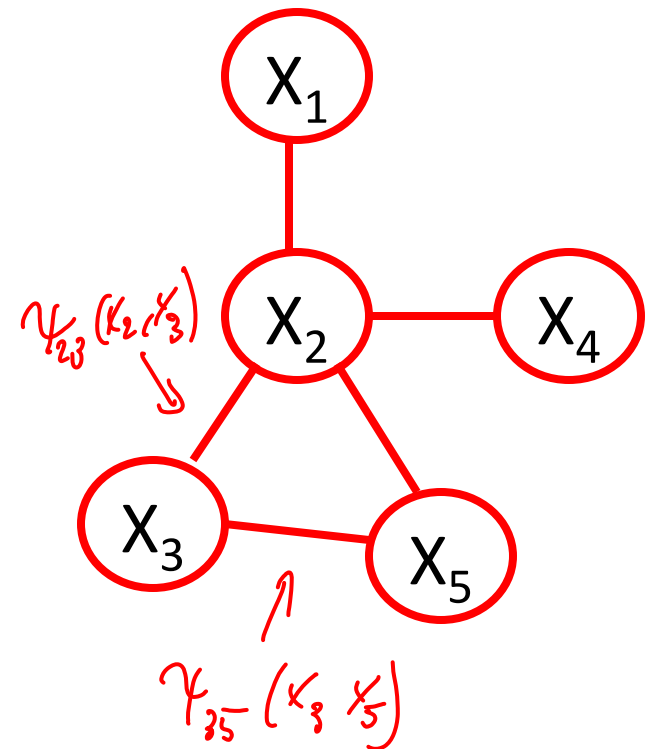
does not have  
MN P-map!

# Exact inference in MNs

- Variable elimination and junction tree inference work exactly the same way!
  - Need to construct junction trees by obtaining chordal graph through triangulation

# Pairwise MNs

- A pairwise MN is a MN where all factors are defined over single variables or pairs of variables
- Can reduce any MN to pairwise MN!



# Logarithmic representation

- Can represent any positive distribution in log domain

$$P(x) = \frac{1}{Z} \prod_i \psi_i(c_i)$$

$$\log P(x) = \sum_i \underbrace{\log \psi_i(c_i)}_{\psi_i(c_i)} - \log Z$$

$$P(x) = \frac{1}{Z} \exp \left( \sum_i \psi_i(c_i) \right)$$

# Log-linear models

- Feature functions  $\phi_i(D)$  defined over cliques

$$\phi_i(x_i, x_{i+1}) = \begin{cases} 1 & \text{if } x_i = x_{i+1} \\ 0 & \text{otherwise} \end{cases}$$

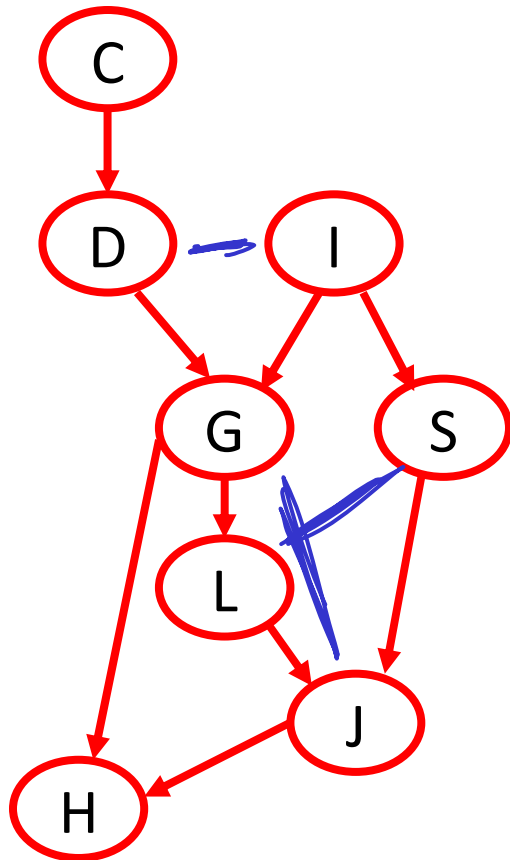
- Log linear model over undirected graph  $G$

- Feature functions  $\phi_1(D_1), \dots, \phi_k(D_k)$
- Domains  $D_i$  can overlap
- Set of weights  $w_i$  learnt from data

$$P(x) = \frac{1}{Z} \exp \left( \sum_i w_i^T \phi_i(C_i) \right)$$

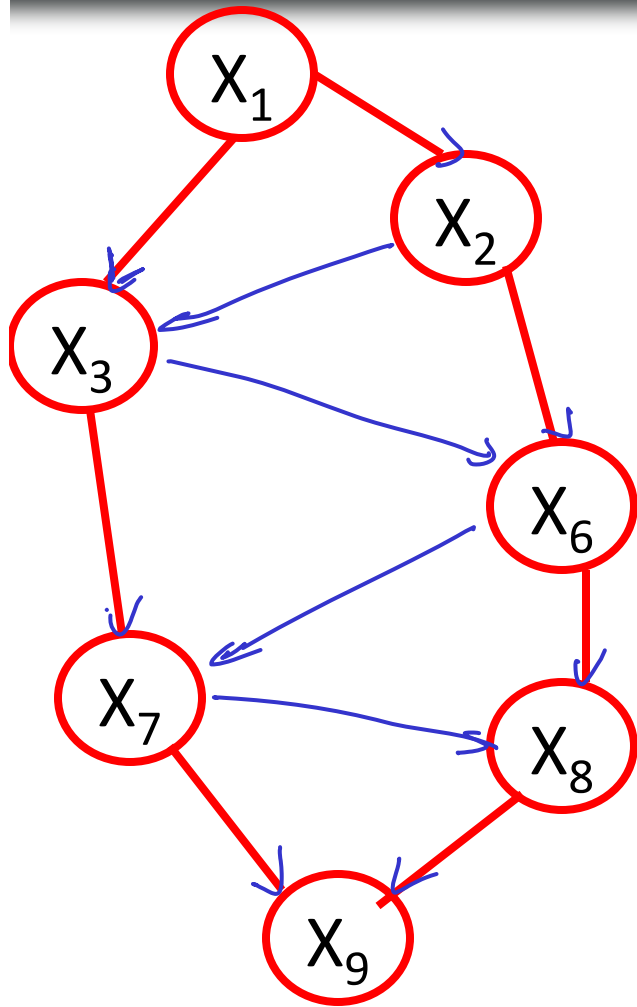


# Converting BNs to MNs



**Theorem:** Moralized Bayes net is minimal Markov I-map

# Converting MNs to BNs



Resulting BN has far fewer  
cond. independencies than original  
MN

$$\begin{array}{ccc} I(G') & \subseteq & I(G) \\ \uparrow & & \uparrow \\ \text{BN} & & \text{MN} \end{array}$$

**Theorem:** Minimal Bayes I-map for MN must be chordal

# So far

- Markov Network **Representation**
  - Local/Global Markov assumptions; Separation
  - Soundness and completeness of separation
- Markov Network **Inference**
  - Variable elimination and Junction Tree inference work exactly as in Bayes Nets
- How about **Learning** Markov Nets?

# Parameter Learning for Bayes nets

$$\begin{aligned}\log P(D|\theta) &= \log \prod_l \prod_i P(X_i^{(l)} | Pa_i^{(l)}; \theta) \\ &= \sum_l \sum_i \log P(X_i^{(l)} | Pa_i^{(l)}; \theta_{X_i(Pa_i)})\end{aligned}$$

Parameter independent

$$\begin{aligned}\frac{\partial}{\partial \theta_{X_i(Pa_i)}} \log P(D|\theta) &= \sum_j \sum_l \frac{\partial}{\partial \theta_{X_i(Pa_i)}} \log P(X_j^{(l)} | Pa_j^{(l)}; \theta_{X_j(Pa_j)}) \\ &= \sum_l \frac{\partial}{\partial \theta_{X_i(Pa_i)}} \log P(X_i^{(l)} | Pa_i^{(l)}; \theta_{X_i(Pa_i)}) \stackrel{!}{=} 0\end{aligned}$$

Problem breaks down into independent subproblems

Learn every CPD independent of others

# Algorithm for BN MLE

Given BN structure  $G$

For each variable  $X_i$

$$\text{learn } \hat{\theta}_{X_i | \text{Pa}_i} = \frac{\text{Count}(X_i, \text{Pa}_i)}{\text{Count}(\text{Pa}_i)}$$

$\Rightarrow$  globally maximum likelihood estimate  
for fixed structure  $G$

# MLE for Markov Nets

- Log likelihood of the data

$$\begin{aligned}
 \log P(D | \theta) &= \sum_{\ell} \log P(x^{(\ell)} | \theta) \\
 &= \sum_{\ell=1}^m \log \frac{1}{Z} \prod_i \psi_i(c_i^{(\ell)}) \\
 &= \sum_{\ell} \sum_i \log \psi_i(c_i^{(\ell)}) - m \log Z \\
 &= m \sum_i \sum_{c_i} \hat{P}(c_i) \underbrace{\log \psi_i(c_i)}_{\substack{\text{in BN} \\ \log P(k_i | Pa_i)}} - \underbrace{m \log Z}_{\text{not in B}}
 \end{aligned}$$

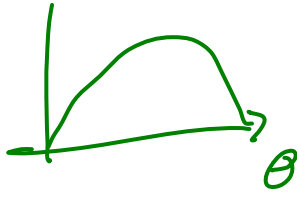
$$Z = Z(\theta) = \sum_x \prod_i \psi_i(c_i) \quad \log Z = \log \sum_x \prod_i \psi_i(c_i)$$

$\uparrow$   
 $\text{arg } \theta$

# Log-likelihood doesn't decompose

- Log likelihood

$$\log P(\mathcal{D} \mid \theta) = m \underbrace{\sum_i \sum_{\mathbf{c}_i} \hat{P}(\mathbf{c}_i) \log \psi_i(\mathbf{c}_i)}_{\text{decomposes nicely}} - \underbrace{m \log Z(\theta)}_{\text{does not decompose}}$$

- $\ell(\mathcal{D} \mid \theta)$  is concave function!  $\log P(\mathcal{D} \mid \theta)$   
No local optima!  
Gradient ascent won't get stuck! 

- Log Partition function  $\log Z(\theta)$  doesn't decompose

# Derivative of log-likelihood

$$\log P(\mathcal{D} \mid \theta) = m \sum_i \sum_{\mathbf{c}_i} \hat{P}(\mathbf{c}_i) \log \psi_i(\mathbf{c}_i) - m \log Z(\theta)$$

$$\begin{aligned} \frac{\partial \log P(\mathcal{D} \mid \theta)}{\partial \psi_i(\mathbf{c}_i)} &= \underbrace{m \sum_j \sum_{\mathbf{c}_j} \hat{P}(\mathbf{c}_j) \frac{\partial}{\partial \psi_i(\mathbf{c}_i)} \log \psi_j(\mathbf{c}_j)}_{\substack{\hat{P}(\mathbf{c}_i) \\ \frac{1}{\psi_i(\mathbf{c}_i)}}} - m \frac{\partial}{\partial \psi_i(\mathbf{c}_i)} \log Z(\theta) \\ &= m \hat{P}(\mathbf{c}_i) \frac{1}{\psi_i(\mathbf{c}_i)} - m \frac{\partial}{\partial \psi_i(\mathbf{c}_i)} \log Z(\theta) \end{aligned}$$



# Derivative of log-likelihood

$$\psi_i =$$

| A | B | $\psi_i(A, B)$ |
|---|---|----------------|
| 0 | 0 | $\psi_i(0, 0)$ |
| 0 | 1 | $\psi_i(0, 1)$ |
| 1 | 0 |                |
| 1 | 1 |                |

$$\frac{\partial \log P(D | \theta)}{\partial \psi_i(\mathbf{c}_i)} = m \frac{\hat{P}(\mathbf{c}_i)}{\psi_i(\mathbf{c}_i)} - m \frac{\partial \log Z(\theta)}{\partial \psi(\mathbf{c}_i)}$$

$$\frac{\partial \log Z(\theta)}{\partial \psi_i(\mathbf{c}_i)} = \frac{\frac{\partial}{\partial \psi_i(\mathbf{c}_i)} Z(\theta)}{Z(\theta)} = \frac{\sum_j P(\mathbf{c}_j | \theta)}{\sum_j \psi_j(\mathbf{c}_i)} = \frac{P(\mathbf{c}_i | \theta)}{\psi_i(\mathbf{c}_i)}$$

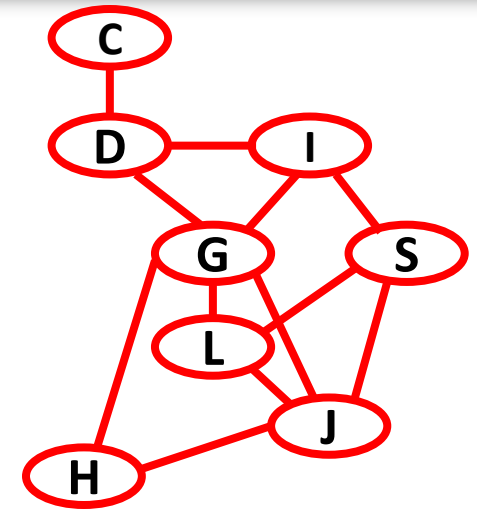
$$\begin{aligned} \frac{\partial Z(\theta)}{\partial \psi_i(\mathbf{c}_i)} &= \frac{\partial}{\partial \psi_i} \sum_x \underbrace{\prod_j \psi_j(\mathbf{c}_j)}_{Z(\theta)} = \sum_x \underbrace{\frac{\partial}{\partial \psi_i} \prod_j \psi_j(\mathbf{c}_j)}_{\substack{0 \text{ if } x \neq \mathbf{c}_i \\ x \text{ inconsistent w } \mathbf{c}_i}} \\ &= \sum_{x \sim \mathbf{c}_i} \prod_{j \neq i} \psi_j(\mathbf{c}_j) \frac{\psi_i(\mathbf{c}_i)}{\psi_i(\mathbf{c}_i)} \\ &= \frac{Z P(\mathbf{c}_i | \theta)}{\psi_i(\mathbf{c}_i)} \end{aligned}$$

# Computing the derivative

- Derivative

$$\frac{\partial \log P(\mathcal{D} \mid \theta)}{\partial \psi_i(\mathbf{c}_i)} = m \frac{\hat{P}(\mathbf{c}_i)}{\psi_i(\mathbf{c}_i)} - m \frac{P(\mathbf{c}_i \mid \theta)}{\psi_i(\mathbf{c}_i)}$$

$$\frac{\partial \log P(\mathcal{D} \mid \theta)}{\partial \psi_G(G=1, D=0, I=1)} = m \frac{\hat{P}(1,0,1)}{\psi_i(1,0,1)} - m \frac{P(1,0,1 \mid \theta)}{\psi_i(1,0,1)}$$



- Computing  $P(\mathbf{c}_i \mid \theta)$  requires inference!

Can do this using VE Junction tree...

- Can optimize using conjugate gradient etc.

## Alternative approach: Iterative Proportional Fitting (IPF)

- At optimum, it must hold that

$$\frac{\partial \log P(\mathcal{D} \mid \theta)}{\partial \psi_i(\mathbf{c}_i)} = m \frac{\hat{P}(\mathbf{c}_i)}{\psi_i(\mathbf{c}_i)} - m \frac{P(\mathbf{c}_i \mid \theta)}{\psi_i(\mathbf{c}_i)} = 0$$

At opt.:  $\frac{\hat{P}(\mathbf{c}_i)}{\psi_i(\mathbf{c}_i)} = \frac{P(\mathbf{c}_i \mid \theta)}{\psi_i(\mathbf{c}_i)}$  "Data agrees with model on marginals"

→ Solve fixed point equation  $\psi_i^{(0)}(\mathbf{c}_i) = 1$

$$\psi_i^{(t+1)}(\mathbf{c}_i) = \psi_i^{(t)}(\mathbf{c}_i) \cdot \frac{\hat{P}(\mathbf{c}_i)}{P(\mathbf{c}_i \mid \theta)}$$

- Must recompute parameters every iteration  $P(\mathbf{c}_i \mid \theta)$

# Parameter learning for log-linear models

- Feature functions  $\phi_i(C_i)$  defined over cliques
- Log linear model over undirected graph  $G$ 
  - Feature functions  $\phi_1(C_1), \dots, \phi_k(C_k)$
  - Domains  $C_i$  can overlap
- Joint distribution

$$P(X_1, \dots, X_n) = \frac{1}{Z} \exp\left(\underbrace{\sum_i w_i^T \phi_i(C_i)}\right)$$

- How do we get weights  $w_i$ ?

# Derivative of Log-likelihood 1

$$\begin{aligned} \frac{\partial \log P(\mathcal{D} \mid \theta)}{\partial w_i} &= m \underbrace{\sum_{\mathbf{c}_i} \hat{P}(\mathbf{c}_i) \frac{\partial w_i^T \phi_i(\mathbf{c}_i)}{\partial w_i}}_{\hat{E}[\phi_i]} - m \frac{\partial \log Z(w)}{\partial w_i} \\ &= m \underbrace{\sum_{\mathbf{c}_i} \hat{P}(\mathbf{c}_i) \phi_i(\mathbf{c}_i)}_{\hat{E}[\phi_i]} - m \frac{\partial \log Z(w)}{\partial w_i} \end{aligned}$$

$$\text{If } \phi_i(x_i, x_{i+1}) = \begin{cases} 1 & \text{if } x_i = x_{i+1} \\ 0 & \text{otherwise} \end{cases}, \quad \hat{E}[\phi_i] = \frac{\text{Count}(x_i = x_{i+1})}{m}$$

# Derivative of Log-likelihood 2

$$\frac{\partial \log P(\mathcal{D} \mid \theta)}{\partial w_i} = m \sum_{\mathbf{c}_i} \hat{P}(\mathbf{c}_i) \phi_i(\mathbf{c}_i) - m \frac{\partial \log Z(w)}{\partial w_i}$$

$$\begin{aligned} \frac{\partial}{\partial w_i} \log Z(w) &= \frac{1}{Z(w)} \frac{\partial}{\partial w_i} \sum_{\mathbf{x}} \exp\left(\sum_i w_i^T \phi_i(\mathbf{c}_i)\right) \\ &= \frac{1}{Z(w)} \sum_{\mathbf{x}} \phi_i(\mathbf{c}_i) \exp\left(\sum_i w_i^T \phi_i(\mathbf{c}_i)\right) \\ &= \sum_{\mathbf{x}} \phi_i(\mathbf{c}_i) \underbrace{\frac{1}{Z} \exp\left(\sum_i w_i^T \phi_i(\mathbf{c}_i)\right)}_{P(\mathbf{x})} \\ &= \sum_{\mathbf{c}_i} \phi_i(\mathbf{c}_i) P(\mathbf{c}_i | w) \\ &= \mathbb{E}_w(\phi_i) \end{aligned}$$

# Optimizing parameters

- Gradient of log-likelihood

$$\frac{\partial \log P(\mathcal{D} \mid w)}{\partial w_i} = m \underbrace{\sum_{\mathbf{c}_i} \hat{P}(\mathbf{c}_i) \phi_i(\mathbf{c}_i)}_{\hat{\mathbb{E}}(\phi_i)} - m \underbrace{\sum_{\mathbf{c}_i} P(\mathbf{c}_i \mid w) \phi_i(\mathbf{c}_i)}_{\mathbb{E}_w(\phi_i)}$$

- Thus,  $w$  is MLE  $\Leftrightarrow \hat{\mathbb{E}}[\phi_i] = \mathbb{E}_w[\phi_i]$

# Regularization of parameters

- Put prior on parameters  $w$   $P(w)$

$$\frac{\partial \log P(\mathcal{D} | w) P(w)}{\partial w_i} = m \underbrace{\sum_{\mathbf{c}_i} \hat{P}(\mathbf{c}_i) \phi_i(\mathbf{c}_i) - \sum_{\mathbf{c}_i} P(\mathbf{c}_i | w) \phi_i(\mathbf{c}_i)}_{\text{last slide}} + \underbrace{\frac{\partial \log P(w)}{\partial w_i}}_{(*)}$$

$$\text{Prior: } P(w) = \mathcal{N}(w; 0, I) \propto \exp\left(-\sum_i w_i^2\right)$$

$$(*) \quad \log P(w) = -\sum_i w_i^2$$

$$\frac{\partial}{\partial w_i} \log P(w) = -2w_i$$



# Summary: Parameter learning in MN

- MLE in BN is easy (score decomposes)
- MLE in MN requires inference (score doesn't decompose)
- Can optimize using gradient ascent or IPF

# Tasks

- Read Koller & Friedman Chapters 20.1-20.3, 4.6.1