

CS137: Electronic Design Automation

Day 8: February 4, 2004
Fault Detection



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Today

- Faults in Logic
- Error Detection Schemes
- Optimization Problem

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Problem

- Gates, wires, memories:
 - built out of physical media
 - may fail

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Device Physics

- Represent a 1 or 0 with charge
 - On a gate, in a memory
- Charge may be disrupted
 - α -particle
 - Ground bounce
 - Noise coupling
 - Tunneling
 - Thermal noise
 - Behavior of individual electrons is statistical

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DRAMs

- Small cells
- Store charge dynamically on capacitor
- Store about 50,000 electrons
- Must be refreshed
 - Data leaks away through parasitic resistance
- α -particle can be 1,000,000 carriers?

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System Reliability

- Device fail with Probability: P_{fail}
- Have N components in system
- All must work for device to work
- $P_{sys} = (1 - P_{fail})^N$

$$P_{sys} = 1 - N \times P_{fail} + \binom{N}{2} \times P_{fail}^2 - \binom{N}{3} \times P_{fail}^3 + \dots$$

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System Reliability

$$P_{sys} = 1 - N \times P_{fail} + \binom{N}{2} \times P_{fail}^2 - \binom{N}{3} \times P_{fail}^3 + \dots$$

- If $N \times P_{fail} \ll 1$
 - $N \times P_{fail}$ dominates higher order terms...

$$P_{sys} \approx 1 - N \times P_{fail}$$

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System Reliability

$$P_{sys} \approx 1 - N \times P_{fail}$$

- $P_{sysfail} \approx N \times P_{fail}$

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Modern System

- 100 Million → 1 Billion Transistors
 - Not to mention wiring...
- > GHz = > 1 Billion Transitions / sec.
- $N = 10^{18}$ per second...

$$P_{sys} \approx 1 - N \times P_{fail}$$

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As we scale?

- N increases
 - Charge/gate decreases
 - Less electrons
 - Higher probability they wander
 - Greater variability in behavior
 - Voltage levels decrease
 - Smaller barriers
 - Greater variability in device parameters
- P_{fail} increases

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Exacerbated at Nanoscale

- Small numbers of dopants (10s)
 - High variability
- Small numbers of electrons (10-1000s?)
 - High variability
 - Highly susceptible to noise
- Small number of molecules
 - May break, decay...

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What do we do about it?

- Tolerate faulty components
- Detect faults
 - Not do anything bad
 - Try it again
 - If statistically unlikely error,
 - high likelihood won't recur.
- ...Focus on detection...

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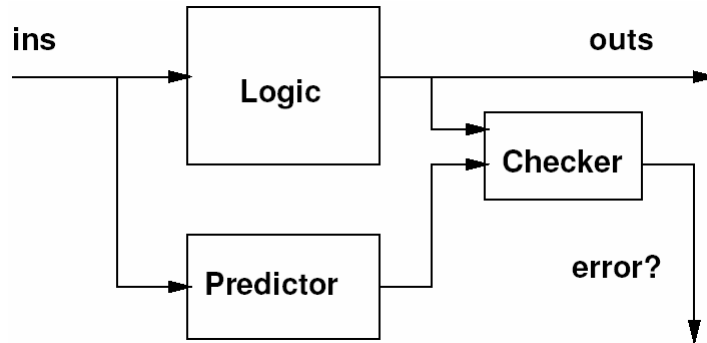
Detect Faults

- **Key Idea:** redundancy
- Include enough redundancy in computation
 - Can tell that an error occurred

What kind of redundancy can we use?

- Multiple copies of logic
- Compute something about result
 - Parity on number of outputs
 - Count of number of 1's in output

Error Detection



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What do we protect against?

- Any n errors
 - Worst-case selection of errors

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Single Error Detection

- If P_{fail} small:
 - No error: $(1-P_{\text{fail}})^N \approx 1-N \times P_{\text{fail}}$
 - One error: $N \times P_{\text{fail}} \times (1-P_{\text{fail}})^{N-1} \approx N \times P_{\text{fail}}$
 - Two errors: $[N \times (N-1) / 2] \times (P_{\text{fail}})^2 \times (1-P_{\text{fail}})^{N-2}$
- Probability of an error going undetected
 - Goes from $\approx N \times P_{\text{fail}}$
 - to $\approx (N \times P_{\text{fail}})^2$
 - For: $N \times P_{\text{fail}} \ll 1$

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Detection Overhead

- Correction and detection circuitry increase circuit size.
- $N_{\text{detect}} > N_{\text{logic}}$
- $N_{\text{detect}} = c N_{\text{logic}}$
- Probability of an error going undetected
 - Goes from $\approx N \times P_{\text{fail}}$
 - to $\approx (c \times N \times P_{\text{fail}})^2$
 - Want: $c^2 \ll 1 / (N \times P_{\text{fail}})$

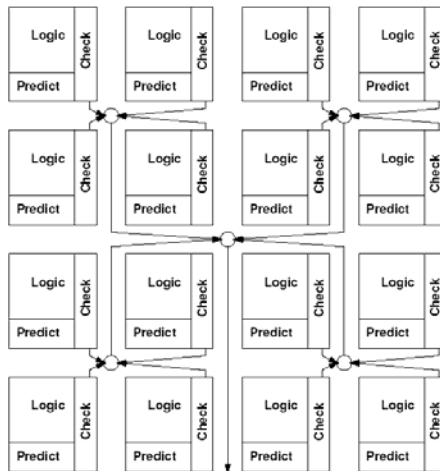
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Reliability Tuning

- Want $N \times P_{\text{fail}}$ small
 - Want: $(c \times N \times P_{\text{fail}})^2$ very small
- Idea:
 - Guard subsystems independently
 - Make N_{sub} suitably small
 - Smaller probability there is a double error localized in this small subsystem

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Guarding Subsystems



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Composing Subsystems

- $P_{\text{sysundetected}} = (N_{\text{sys}}/N_s) P_{\text{subundetected}}$
- $P_{\text{subundetected}} = (c \times N_s \times P_{\text{fail}})^2$
- $P_{\text{sysundetected}} = (N_{\text{sys}}/N_s) (c \times N_s \times P_{\text{fail}})^2$
- $P_{\text{sysundetected}} = N_{\text{sys}} \times N_s \times (c \times P_{\text{fail}})^2$
- **Extermes:**
 - $N_s = N_{\text{sys}}$
 - $N_s = 1$

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Problem

- Generate logic capable of detecting any single error

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Terminology

- **Fault-secure:** system never produces incorrect code word
 - *Either* produces correct result
 - *Or* detects the error
- **Self-testing:** for every fault, there is some input that produces an incorrect code word
 - That detects the error

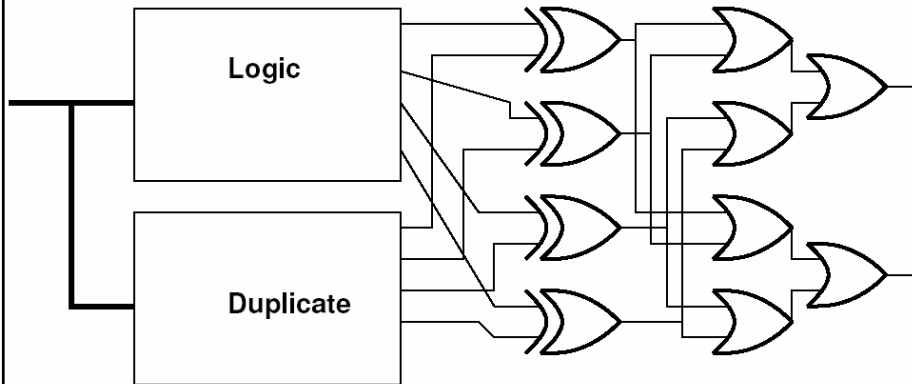
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Terminology

- **Totally Self Checking:** system is both *fault-secure* and *self-testing*.

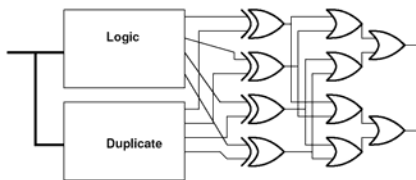
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Duplication



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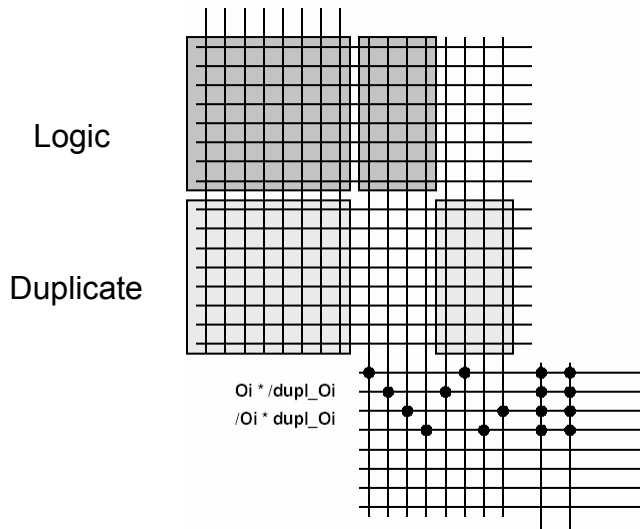
Duplication



- N original gates
- Duplicate: + N
- O outputs
 - O xors
 - $O/2 \times 2 \times 2$ ors
- $O < N$
- $2 < c < 5$

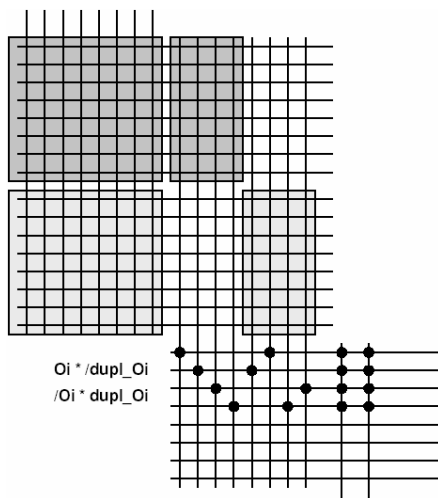
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Duplication with PLA



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PLA Duplication



- N product terms in original
- N in duplicate
- 2 O product terms for matching
- $O \leq N$
- $2 < c < 4$

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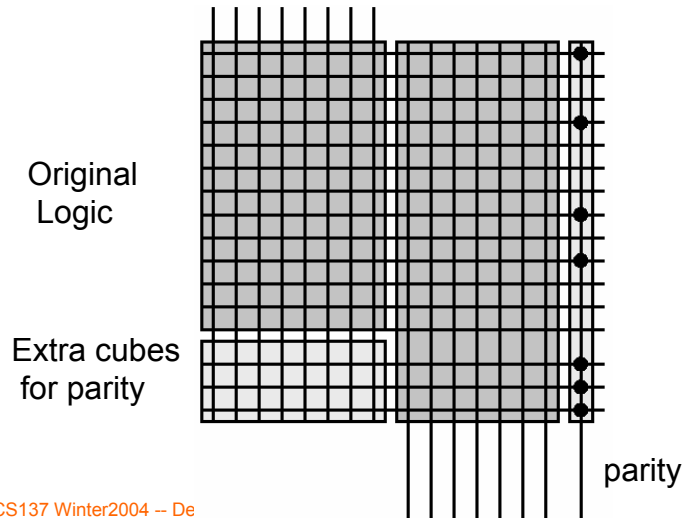
Can we do better?

- Seems like overkill to compute twice?

Idea

- Encode so outputs have some checkable property
 - E.g. parity

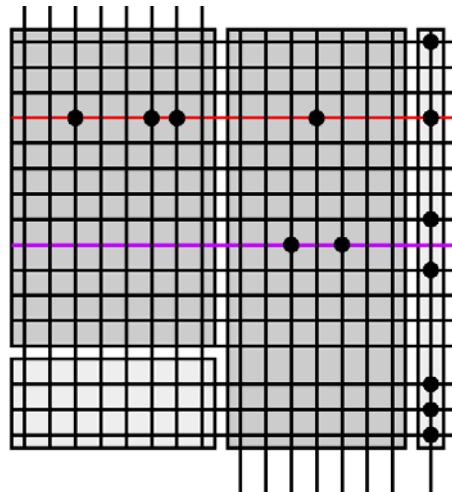
Will this work?



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Problem

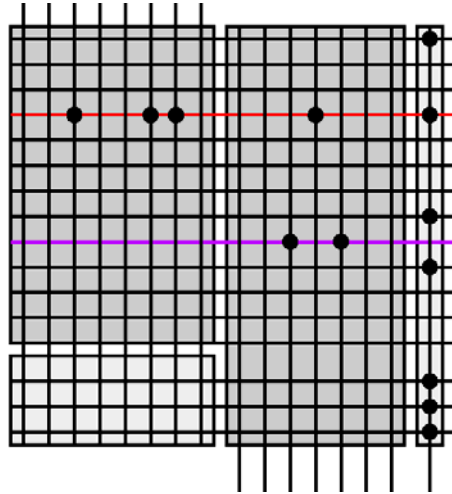
- Single fault may produce multiple output errors



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How Fix?

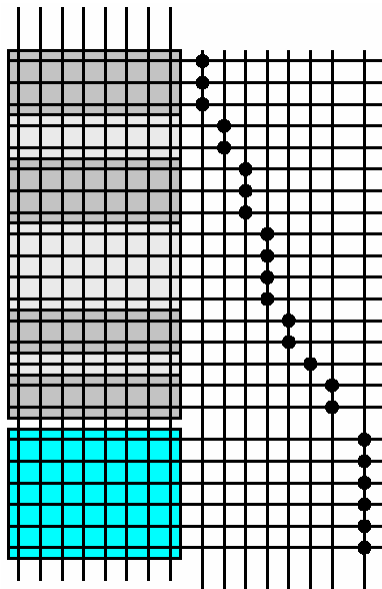
- How do we fix?



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No Logic Sharing

- No sharing
- Single fault effects single output



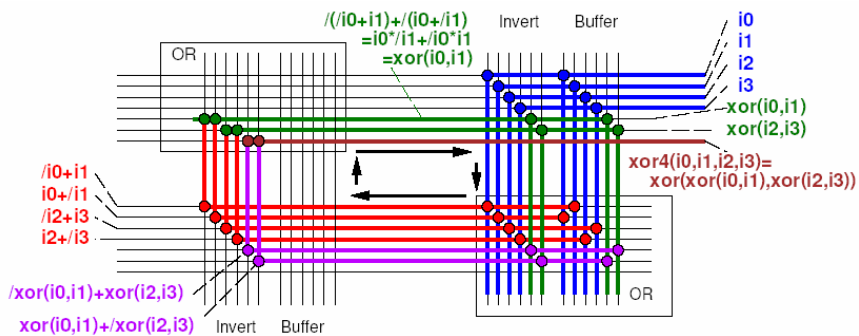
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Parity Checking

- To check parity
 - Need xor tree on outputs/parity
 - $[(O+1)/2] \times 2 \times 2 = 2(O+1)$ xors
- For PLA
 - xor would blow up
 - Wrap multiple times
 - 2 product terms per xor
 - $4 \times O$ product terms

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nanoPLA Wrapped xor



Note: two planes here just for buffering/inversion

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Better or Worse than Dual?

- Depends on sharing in logic
- Typical results from Mitra [ITC2002]

Circuit	Identical Duplex	Diverse Duplex	Parity	Berger Code	Bose - Lin
Z5xp1	822	836	840	1335	1068
inc	743	751	692	854	807
squar5	507	485	465	627	570
ex5.20	646	649	593	815	755
misex1	412	423	367	468	488
sao2	754	787	748	983	864
rd73	474	480	683	853	763
rd84	642	684	971	1135	1056

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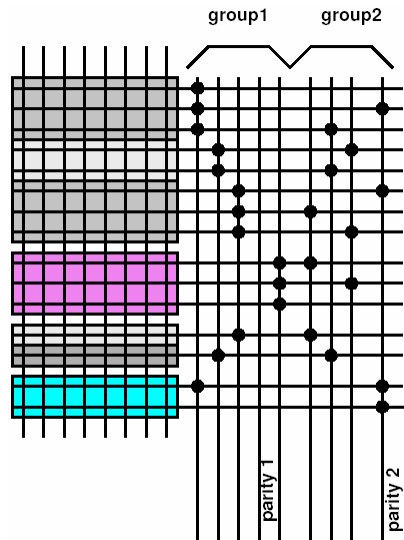
Can we allow sharing?

- When?

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Multiple Parity Groups

- Can share with different parity groups
- Common error flagged in both groups



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Better or Worse than Dual?

- Typical results from Mitra [ITC2002]

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(parity here includes sharing)

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Project Assignment

- Assignments #3 & #4
 - Out on Monday
- Provide an algorithm for identifying parity groups
 - Keep single error detection property
 - Minimize pterms

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Admin

- Assignment #2 due Friday

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Big Ideas

- Low-level physics imperfect
 - Statistical, noisy
- Larger devices → greater likelihood of faults
- Redundancy
- Self-checking circuits