Processes and Threads

• As previously described, processes have one sequential thread of execution

• Increasingly, operating systems offer the ability to have multiple concurrent threads of execution in a process
  • Individual threads can execute only one instruction at a time
  • Multiple threads in a process allow multiple tasks to be performed concurrently, at the same time

• Requires changes to the process model:
  • CPU state can no longer be managed on a per-process basis
  • Must manage CPU state on a per-thread basis
  • All other resources can be managed on a per-process basis
Processes and Threads (2)

**Single-threaded process**
- Per-process items:
  - Address space / page table
  - Program text (i.e. the code)
  - CPU registers
  - Program counter
  - Stack and stack pointer
  - Global variables
  - Memory heap
  - Signal handlers
  - Open files, sockets, etc.
  - Child processes

**Multithreaded process**
- Per-process items:
  - Address space / page table
  - Program text
  - Global variables
  - Memory heap
  - Signal handlers
  - Open files, sockets, etc.
  - Child processes
- Per-thread items:
  - CPU registers
  - Program counter
  - Stack and stack pointer
Why Multithreaded Processes?

• Two big reasons why multithreading is desirable:
  • **Reason 1**: Performance (obvious)
  • **Reason 2**: A cleaner abstraction for concurrent operations

• Lots of ways that multithreading can improve performance

• **Responsiveness**:
  • Applications that perform slow or long-running tasks can perform them using background threads
  • A foreground thread responds to user interactions immediately
  • Responsive applications = happy users 😊

• Web browsers are a common example of this pattern
  • User-interface thread draws the web page, handles mouse clicks
  • A pool of background threads handles downloading of web pages from remote web servers
  • UI thread updates display as downloaded files become available
Multithreading: Responsiveness

• Common web browser pattern:
  • User-interface thread draws the web page, handles mouse clicks
  • A pool of background threads handles downloading of web pages from remote web servers

• Does this require multiple CPUs to yield a benefit?
  • **NO!**
    • Background threads will usually be blocked on I/O, or waiting for work to do – won’t occupy the CPU
    • Similar case for UI thread – waiting for user interaction

• Even with a single physical processor, multithreading can greatly improve application responsiveness
  • Particularly in cases where most tasks are I/O bound
Multithreading: Scalability

- **Example:** a large scientific/mathematical computation
  - Instead of performing this computation in a single thread, split it into multiple concurrently executing threads

- **Does this require multiple CPUs to yield a benefit?**
  - **YES!**
    - Threads will mostly be CPU-bound, not I/O-bound
    - If there is only one CPU in the system, multiple threads will probably make the program **slower** instead of faster
      - (extra context-switches, synchronization overhead, etc.)

- **If there are multiple CPUs in the system:**
  - A single-threaded process **cannot** take advantage of multiple CPUs
  - Only way to utilize multiple CPUs is to run multiple processes, or to run a process with multiple threads
  - Multithreading facilitates **scalability** with available hardware
Multithreading: Scalability (2)

• A major difference between concurrency and parallelism!

• **Concurrency** means that multiple tasks have overlapping logical control flows

• Concurrency does not require multiple processors
  • A one-CPU system can achieve this by switching back and forth between concurrent tasks at appropriate points in time
  • Concurrency doesn’t necessarily imply that multiple tasks’ instructions are being executed at the same time, just that their execution is overlapping/interleaved in some way

• **Parallelism** means that multiple tasks are actually executing at the same time
  • i.e. multiple processors are executing different tasks’ instructions at exactly the same time
Multithreading: Scalability (3)

- Example: a large scientific/mathematical computation
  - Instead of performing this computation in a single thread, split it into multiple concurrently executing threads
- If a system has multiple CPUs, can improve computation’s performance by running one thread per CPU
  - Threads will actually execute in parallel
- Assume program takes 1 unit of time to complete on 1 CPU
  - Ideally, running the program on \( N \) CPUs will result in it taking \( 1/N \) the time to complete (i.e. a speedup of \( N \))
- The reality isn’t always so nice…
  - Most computations have certain parts that must be performed sequentially, and cannot be parallelized
  - The sequential parts restrict the maximum possible speedup that can be achieved by parallelizing the task
Amdahl’s Law

• Amdahl’s Law is a simple formula that captures this issue
• Given: a task where $S$ is the percentage of the task that must be executed serially (i.e. cannot be parallelized)
  • On a single-processor machine the task takes 1 unit of time to run
  • On an $N$-processor machine, the task will take $S + (1 - S) / N$ units of time to run
  • The speedup due to parallelism will be $(S + (1 - S) / N)^{-1}$
• Example: a task with 10% that must be run serially
  • 1.8x speedup on 2 CPUs
  • 3.1x speedup on 4 CPUs
  • 4.7x speedup on 8 CPUs
  • As $N \to \infty$, speedup $\to 10x$, and that’s it. 😞
Amdahl’s Law (2)

• Amdahl’s Law is bad news for speeding up fixed-size tasks by adding processors…

• Many tasks are variable in size:
  • Given more computing resources, users will increase the size of the task to use all available computing resources
  • Focus isn’t solely on reducing the time to complete the task

• Also, many variable-size tasks have this characteristic:
  • As the task’s size increases, the size of parallelizable part of the task increases faster than size of the serial part of the task
  • Percentage of the task that must be executed serially will decrease!

• Such tasks still see improved performance by increasing parallelism
  • Formulated as Gustafson-Barsis’ Law (1988)
  • Not a contradiction of Amdahl’s Law, just different constraints
Multithreading: Economy

• Multithreaded processes have two other performance-related benefits: resource sharing and economy

• Threads are generally much faster to create and destroy than processes
  • Fewer resources must be allocated or released: most resources are managed on a per-process basis

• Context-switching between multiple threads in the same process tends to be much faster
  • Threads share the same address space: don’t need to change the current page table being used, etc.
  • (Switching between threads in different processes is still slower.)

• Sharing resources (e.g. files, sockets) between threads is much easier than sharing them between processes
Multithreading: Abstractions

- Another benefit of threads: a cleaner abstraction
- Why are long-running system calls blocking, anyway?
  - i.e. why do they force the process to wait until request is completed
- Blocking operations are simply much easier to use!
- Alternative: asynchronous (non-blocking) operations
  - Initiate a long-running operation in the system.
  - Periodically check to see if the operation is complete.
    If not, go do other things while you wait.
  - When operation finally completes, go on to next steps in your task.
- Most systems provide asynchronous I/O APIs alongside blocking I/O APIs
  - Primarily used for asynchronous networking I/O
Asynchronous I/O

- UNIX API examples:
  ```c
  select(int nfds, fd_set *readfds, fd_set *writefds,
         fd_set *exceptfds, timeval *timeout)
  poll(pollfd *fds, nfds_t nfds, int timeout)
  ```

- Both allow a collection of file-descriptors to be monitored
  - Returns if a file-descriptor can be read or written without blocking, if an error occurs on a file-descriptor, or if the call times out

- Applications usually use non-blocking I/O when they want to achieve very high performance
  - (OSes heavily optimize these functions to be fast and scalable)
- However, greatly increases implementation complexity
Example: Web Server

• Basic webserver operation, per request:
  • Accept an incoming socket connection
  • Receive the HTTP request over the socket
  • Access the file(s) specified in the HTTP request
  • Send an HTTP response back to the client

• Of course, want to handle requests as fast as possible
  • Even handle multiple incoming requests concurrently, if possible

• Most of these operations are long-running tasks

• Can imagine how the webserver would be implemented with these various approaches:
  • Single-threaded process with blocking network I/O
  • Single-threaded process with non-blocking network I/O
  • Multithreaded process with blocking network I/O
Web Server, Single-Threaded Style

- If webserver is implemented as a single-threaded process with blocking network I/O:
  - Web server can’t do anything else while receiving a request, or sending a response (basically always blocked on I/O)
  - Web clients will spend a lot of time waiting on the server
  - Can code this very easily though: write a loop that just processes each request and sends each response in sequence

- Using non-blocking I/O allows us to achieve concurrency without using multiple threads
  - Allows us to overlap the networking operations of multiple requests/responses (concurrency!)
  - A given request/response will still take the same time to complete, but overall throughput will be much higher
  - Server is more likely to be CPU-bound, rather than I/O-bound
Web Server, Single-Threaded Style (2)

- Webserver with non-blocking I/O:
  - Will have many sockets open to many clients, servicing requests
- Must keep track of the state of every request/response:
  - What stage of request/response cycle is each connection at?
  - Receiving the request? If so, where is request data being buffered, and where does new data get written in the buffer?
  - Sending the response? If so, how much of the file has been sent? Or, is the webserver sending an error response?
Web Server, Single-Threaded Style (3)

• Web server main-loop:
  • Wait for some socket(s) to become active (i.e. can send/receive without blocking)
  • For each active socket, get the current state of that socket’s interaction, and do as much work as possible without blocking
  Once all active sockets are handled, go back and wait some more!

• Server basically implements a finite state machine for each open connection
Web Server, Single-Threaded Style (4)

• Example pseudocode:
  if stage is RECV_REQUEST:
    receive more data into input buffer
    if all data received:
      generate response into output buffer
      stage = SEND_RESPONSE
  else if stage is SEND_RESPONSE:
    send more data from output buffer
    if all data sent:
      close connection
      remove state and connection from arrays

• Responsibility of implementing concurrency of tasks has fallen on the webserver, not on the OS 😞
  • (It’s complicated, and prone to bugs.)
Web Server, Multithreaded Style

• Multithreaded processes allow applications to achieve concurrency while still using blocking system calls
  • The operating system implements the concurrency
  • Apps only have to worry about coordination between threads

• Multithreaded webserver with blocking network I/O:
  • Each thread executes a simple sequence of steps, identical to the original single-threaded webserver with blocking calls:
    • Receive the HTTP request over the socket
    • Access the file(s) specified in the HTTP request
    • Send an HTTP response back to the client
  • Can start as many threads as we need!
  • (With an I/O-bound problem like this, can usually start many more threads than CPUs in the system, and still see performance gains)
Aside: Non-Blocking I/O

- Non-blocking I/O in a single-threaded process is pretty complicated…
- Nonetheless, it is often the fastest possible approach! Used by a number of highly scalable servers.
  - Avoids a significant amount of overhead from e.g. context-switching between threads, kernel scheduler invocations, etc.
  - Reduces space requirements as well (e.g. don’t need stacks for multiple threads, can optimize storage of task details
  - One thread waiting on a large collection of sockets is much more efficient than many threads each waiting on one socket
- Example: NGINX (“engine-x”) web server
  - Easily supports 10000+ concurrent connections (C10K problem)
  - Used by Facebook, Dropbox, Wikipedia, Wordpress, etc.
Implementing Threads

• Several different approaches to implementing threads
• Can implement multithreading entirely in user mode
  • a.k.a. user-mode/userspace threading libraries, or “user threads”
  • Kernel only provides a process abstraction, is unaware of threads
• Excellent for platforms that don’t support multithreading at the kernel level (less common now)
• Such libraries frequently provide cooperative multithreading
  • Difficult and grungy to set up a periodic timer to drive thread preemption
  • Often, smallest timer interval available in user-space is still pretty large
  • Frequent timer interrupts can degrade performance of other applications, etc.
User Threads

• Benefit: user-mode thread management is very fast
  • No trapping to kernel to create/destroy threads, switch threads, etc.

• Problem: frequently want to use threads to achieve concurrency in programs with blocking system calls
  • Blocking system calls require a trap into the kernel…
  • Kernel will simply context-switch to another process!
  • When a thread makes a long-running call, other user-space threads won’t get to run

• Problem: frequently want threads to take advantage of multiple CPUs
  • Again, kernel is unaware of threads; it only schedules processes on CPUs

• User threading is very limited
Kernel Threading Support

- Other option is to provide threading support in the kernel
  - Basically all modern operating systems have this capability now
- Kernel can be more intelligent about thread scheduling
- Multithreading and blocking system calls:
  - If one thread in a process makes a system call and blocks, but another thread in same process can proceed, switch to 2nd thread
  - Saves some overhead of context-switching (e.g. MMU updates)
- Multithreading and parallelism:
  - On multiprocessor systems, the kernel can schedule threads from the same process on different CPUs
- Drawback: thread-management calls now require a trap
  - Creating/desroying threads, context-switch between threads, etc.
Kernel Threads

- Ultimately, the operating system is what implements and provides multitasking support...
- Each thread a user application has, must correspond to some schedulable, kernel-level task
  - (Multiple user-level threads can map to the same kernel task)
- The minimal form of schedulable task inside the kernel is called a kernel thread
  - Thread's context contains CPU registers, program counter, stack, stack pointer, flags, etc.
  - This is not a process! Every process may have a corresponding kernel thread, but the kernel thread itself is very lightweight.
- Individual kernel threads can become blocked, can be resumed, etc.
Threading Models

- Different threading models have different ways of mapping “user threads” (threads in an application) to kernel threads.
- The **many-to-one threading model** maps many user threads to a single kernel thread.
  - In this case, the kernel thread basically manages a process.
- This model corresponds to the user-mode threading library implementation.
- Example:
  - All user threads in a process are mapped to one kernel thread.
  - One user thread decides to perform a blocking operation…
  - The kernel thread becomes blocked, preventing all other user threads from progressing.
- The GNU Portable Threads library follows this model.
**Threading Models (2)**

- The **one-to-one threading model** maps every user thread to its own kernel thread
- This model corresponds to the kernel-supported threading library implementation
- Example:
  - Each user thread in a process is mapped to its own kernel thread
  - One user thread decides to perform a blocking operation…
  - That kernel thread becomes blocked…
  - Since every other user thread has its own kernel thread, other user threads are unaffected by the blocked thread
- This is the model that most OSes now provide
  - Tends to be the most straightforward to implement
Threading Models (3)

• A few operating systems implement a many-to-many or hybrid threading model
  • Many user threads mapped to many (usually fewer) kernel threads
• Premise:
  • Both user-mode threading and kernel threading have benefits!
  • User-space threading is very lightweight and inexpensive, but weak
  • Kernel threading is powerful, but slower and more resource-heavy
• Given: $N$ user threads, $M$ kernel threads ($M < N$)
  • Try to map user threads to kernel threads to maximize benefits
  • e.g. creating and destroying many short-lived threads will be cheap
  • e.g. many cooperating user threads can be mapped to one kernel thread, reducing syscalls and kernel-level context switches
  • e.g. if a user thread blocks on I/O frequently, assign it a dedicated kernel thread to keep it from blocking other user threads
Threading Models (4)

- Many-to-many model appears to be the best solution…
- Unfortunately, it is extremely difficult to implement
  - So difficult that most OSes simply use the one-to-one model
  - Windows 7 implements a hybrid threading model
    - Previous versions of Windows implemented a one-to-one model
- Problem: thread management code is spread between userspace library and the kernel
  - These layers must collaborate closely to maximize the performance benefits of combining the two threading models
Threading Models (5)

- Without coordination, user threading library has little hope of effectively managing the mapping to kernel threads.
- Can user-thread layer intercept blocking syscalls?
  - If so, other user threads on same kernel thread can be reassigned to prevent them from being blocked.
  - If not, very likely that user threads sharing a kernel thread will become blocked.
- Can user-thread layer access kernel-level details of thread behavior?
  - e.g. if kernel reports compute-intensive tasks, user thread library can assign them to different kernel threads to run on multiple CPUs.
  - If not, system can't take full advantage of multiple CPUs to maximize performance.
Scheduler Activations

- Clearly, user-space threading library and kernel threading layer must communicate for hybrid threading to work...
- Most widely used approach called **scheduler activations**
- Kernel allows processes to register for scheduling events
  - “A kernel thread was preempted”
  - “A kernel thread is about to block”
  - “A kernel thread is about to be unblocked”
  - “A kernel thread caused a page fault”
  - etc.
- When kernel scheduler detects such an event, it makes an **upcall** to the user-space event handler
  - The **upcall handler** responds to the event, then the kernel goes on with its tasks
Scheduler Activations (2)

• The user-space threading library can register an upcall handler to receive kernel scheduling events
  • Library can map user threads to kernel threads more intelligently!
  • Library can even request additional kernel threads on behalf of the app, depending on app’s thread behavior
    • (Kernel threads are sometimes called “lightweight processes” in this approach)
• Problem: this mechanism can greatly affect system performance
  • Additional transitions between user-mode and kernel-mode during scheduling…
  • More time spent scheduling, and less time spent executing the application’s code
• Approach hasn’t seen widespread adoption at this point
Scheduler Activations (3)

- Marcel threading library is most notable example of “scheduler activations” mechanism
  - http://runtime.bordeaux.inria.fr/marcel/
Next Time

• More kernel thread implementation details